

Deformations of infinite-dimensional Lie algebras, exotic cohomology, and integrable nonlinear partial differential equations

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Integrable differential equations

Integrable nonlinear partial differential equations:
Lax representations (zero-curvature representations,
Wahlquist–Estabrook prolongation structures, integrable
extensions, IST, differential coverings...):

- soliton solutions
- Bäcklund transformations
- nonlocal symmetries and nonlocal conservation laws
- recursion operators
- Darboux transformations
- ...

UNSOLVED PROBLEM: to find conditions of existence of a
Lax representation for a given PDE.

Lax representations

A Lax representation for a differential equation \mathcal{E}

$$F(x^i, u, u_{x^i}, u_{x^i x^j}, \dots) = 0, \quad i, j, k \in \{1, \dots, n\},$$

is defined by the over-determined system

$$w_{a,x^k} = T_{ak}(x^i, u, u_{x^i}, u_{x^i x^j}, \dots, w_b), \quad a, b \in \mathbb{N},$$

whose compatibility conditions coincide with \mathcal{E} .

Geometrically: a flat connection on $\mathcal{E} \times \mathcal{W} \rightarrow \mathcal{E}$,

$$D_{x^k} \mapsto \tilde{D}_{x^k} = D_{x^k} + \sum_a T_{ak}(x^i, u, u_{x^i}, u_{x^i x^j}, \dots, w_b) \frac{\partial}{\partial w_a}$$

such that $[\tilde{D}_{x^i}, \tilde{D}_{x^j}] = 0 \Leftrightarrow F(x^i, u, u_{x^i}, u_{x^i x^j}, \dots) = 0$,

or by the ideal of the Wahlquist–Estabrook forms

$$\tau_a = dw_a - \sum_k T_{ak}(x^i, u, u_{x^i}, u_{x^i x^j}, \dots, w_b) dx^k$$

such that

$$d\tau_a \equiv \sum_b \eta_{ab} \wedge \tau_b \mod \langle \text{contact forms on } \mathcal{E} \rangle.$$

Lax representations

Definitions, details, examples:

- H.D. Wahlquist, F.B. Estabrook, J. Math. Phys., 1975, Vol. 16, 1–7.
- ...
- I.S. Krasil'shchik, A.M. Vinogradov, Acta Appl. Math., 1984, Vol. 2, 79–86, Acta Appl. Math., 1989, Vol. 15, 161–209.
- Krasil'shchik I.S., Lychagin V.V., Vinogradov A.M. Geometry of jet spaces and nonlinear partial differential equations. N.Y.: Gordon and Breach, 1986
- ...

Exotic cohomology

Exotic (deformed, twisted, covariant, ...) cohomology: geometry of Poisson manifolds, Morse theory of multi-valued functionals, symplectic geometry, algebraic topology, theory of Lie algebras.

- A. Lichnerowicz, 1977,
- E. Witten 1982,
- M. Atiyah, R. Bott, 1984
- S.P. Novikov, 1986, 2002, 2005
- ...

Exotic cohomology of Lie algebras

\mathfrak{g} – Lie algebra over \mathbb{R} , $\rho: \mathfrak{g} \rightarrow \text{End}(V)$ – its representation,

$$C^k(\mathfrak{g}, V) = \text{Hom}(\Lambda^k(\mathfrak{g}), V), \quad k \geq 1,$$

$$\begin{aligned} d\theta(X_1, \dots, X_{k+1}) &= \sum_{q=1}^{k+1} (-1)^{q+1} \rho(X_q) (\theta(X_1, \dots, \hat{X}_q, \dots, X_{k+1})) \\ &+ \sum_{1 \leq p < q \leq k+1} (-1)^{p+q} \theta([X_p, X_q], X_1, \dots, \hat{X}_p, \dots, \hat{X}_q, \dots, X_{k+1}), \end{aligned}$$

the Chevalley-Eilenberg differential complex

$$\dots \xrightarrow{d} C^k(\mathfrak{g}, V) \xrightarrow{d} C^{k+1}(\mathfrak{g}, V) \xrightarrow{d} \dots$$

Its cohomology

$$H^k(\mathfrak{g}, V) = \frac{\ker d: C^k(\mathfrak{g}, V) \longrightarrow C^{k+1}(\mathfrak{g}, V)}{\text{im } d: C^{k-1}(\mathfrak{g}, V) \longrightarrow C^k(\mathfrak{g}, V)},$$

$\rho_0: X \mapsto 0 \Rightarrow$ cohomology with trivial coefficients $H^*(\mathfrak{g})$.

Exotic cohomology of Lie algebras

Suppose $H^1(\mathfrak{g}) \neq \{0\}$, take ω such that $[\omega] \in H^1(\mathfrak{g})$. For $\lambda \in \mathbb{R}$ define

$$d_{\lambda\omega}\theta = d\theta + \lambda\omega \wedge \theta$$

From $d\omega = 0$ it follows that $d_{\lambda\omega}^2 = 0$, therefore the differential complex

$$\dots \xrightarrow{d_{\lambda\omega}} C^k(\mathfrak{g}, \mathbb{R}) \xrightarrow{d_{\lambda\omega}} C^{k+1}(\mathfrak{g}, \mathbb{R}) \xrightarrow{d_{\lambda\omega}} \dots$$

is defined. Its cohomology groups $H_{\lambda\omega}^*(\mathfrak{g})$ are referred to as **exotic cohomology groups** of \mathfrak{g} .

REMARK. $H_{\lambda\omega}^*(\mathfrak{g})$ coincide with the cohomology of \mathfrak{g} with coefficients in the one-dimensional representation $\rho_{\lambda\omega}: \mathfrak{g} \rightarrow \mathbb{R}$, $\rho_{\lambda\omega}: X \mapsto \lambda\omega(X)$.

Exotic cohomology of Lie algebras

EXAMPLE. Consider a Lie algebra \mathfrak{h} with generators X_0, \dots, X_3 and non-zero commutators

$$[X_0, X_1] = -X_1,$$

$$[X_0, X_2] = -2X_2,$$

$$[X_0, X_3] = -3X_3,$$

$$[X_1, X_2] = -X_3.$$

For the dual 1-forms ([Maurer–Cartan forms](#)) ω_i such that $\omega_i(X_j) = \delta_{ij}$ the [structure equations](#) hold:

$$d\omega_0 = 0,$$

$$d\omega_1 = \omega_0 \wedge \omega_1,$$

$$d\omega_2 = 2\omega_0 \wedge \omega_2,$$

$$d\omega_3 = 3\omega_0 \wedge \omega_3 + \omega_1 \wedge \omega_2.$$

$$H^1(\mathfrak{h}) = \mathbb{R}[\omega_0] = \mathbb{R}\omega_0.$$

$$H^2(\mathfrak{h}) = \{0\} \Rightarrow \mathfrak{h} \text{ has no central extensions.}$$

Exotic cohomology of Lie algebras

We have

$$H_{\lambda \omega_0}^2(\mathfrak{h}) = \begin{cases} \mathbb{R}[\omega_1 \wedge \omega_3], & \lambda = -4, \\ \mathbb{R}[\omega_2 \wedge \omega_3], & \lambda = -5, \\ \{0\}, & \lambda \notin \{-5, -4\} \end{cases}$$

From

$$d_{-4\omega_0}(\omega_1 \wedge \omega_3) = 0$$

it follows that equation

$$d_{-4\omega_0}\omega_4 = \omega_1 \wedge \omega_3$$

with unknown 1-form ω_4 is compatible with the structure equations of \mathfrak{h} \Rightarrow two additional structure equations

$$d\omega_4 = 4\omega_0 \wedge \omega_4 + \omega_1 \wedge \omega_3,$$

$$d\omega_5 = 5\omega_0 \wedge \omega_5 + \omega_2 \wedge \omega_3,$$

\Rightarrow two-dimensional extension $\tilde{\mathfrak{h}} = \mathfrak{h} \oplus \langle X_4, X_5 \rangle$,

$$[X_0, X_4] = -4X_4, \quad [X_1, X_3] = -X_4,$$

$$[X_0, X_5] = -5X_5, \quad [X_2, X_3] = -X_5.$$

Cartan's method of equivalence & symmetries of DEs

The main idea: to apply the above trick to the structure equations of the contact symmetry pseudo-group of the PDE under the study.

For a given PDE \mathcal{E} the Maurer–Cartan forms and the structure equations of the symmetry pseudo-group $Sym(\mathcal{E})$ can be found algorithmically (using derivation and operations of linear algebra) by means of É. Cartan's method of equivalence.

- É. Cartan. Œuvres Complètes. Paris: Gauthier - Villars, 1953
- P.J. Olver. Equivalence, invariants, and symmetry. Cambridge: CUP, 1995
- M. Fels, P.J. Olver. Acta Appl. Math., 1998, Vol. 51, 161–213
- O.M. J. Phys. A: Math. Gen., 2002, Vol. 35, 2965–2977
- O.M. J. Math. Sci., 2006, Vol. 135, 2680–2694

Lax representations & exotic cohomology

EXAMPLE. The potential Khokhlov–Zabolotskaya equation

$$u_{yy} = u_{tx} + u_x u_{xx} \tag{\mathcal{E}}$$

The structure equations of $Sym(\mathcal{E})$:

$$d\alpha = 0,$$

$$d\Theta_0 = \nabla\Theta_0 \wedge \Theta_0,$$

$$d\Theta_1 = \alpha \wedge \Theta_1 + \nabla\Theta_1 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_0 \wedge \Theta_1,$$

$$d\Theta_2 = 2\alpha \wedge \Theta_2 + \nabla\Theta_2 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_1 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_0 \wedge \Theta_2,$$

$$d\Theta_3 = 3\alpha \wedge \Theta_3 + \nabla\Theta_3 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_2 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_1 \wedge \Theta_2,$$

$$d\Theta_4 = 4\alpha \wedge \Theta_4 + \nabla\Theta_4 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_3 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_2 \wedge \Theta_2 - \frac{1}{3}\nabla\Theta_0 \wedge \Theta_4,$$

where $\Theta_m = \sum_{n=0}^{\infty} \frac{h^n}{n!} \theta_{m,n}$, $0 \leq m \leq 4$,

$$\nabla\Theta_m = \frac{\partial}{\partial h} \Theta_m = \sum_{n=0}^{\infty} \frac{h^n}{n!} \theta_{m,n+1}, \quad dh = 0, \quad \theta_{3,0} = 0.$$

Lax representations & exotic cohomology

The Maurer–Cartan forms:

$$\alpha = p^{-1} dp,$$

$$\theta_{0,0} = q dt,$$

$$\theta_{1,0} = p q^{2/3} (dy + a_1 dt),$$

$$\theta_{2,0} = p^2 q^{1/3} \left(dx + \frac{2}{3} a_1 dy + a_2 dt \right),$$

$$\theta_{4,0} = p^4 q^{-1/3} (du - u_t dt - u_x dx - u_y dy).$$

REMARK: All the other Maurer–Cartan forms can be found inductively by integration:

$$d\theta_{0,0} = \theta_{0,1} \wedge \theta_{0,0} \Rightarrow dq \wedge dt = \theta_{0,1} \wedge q dt \Rightarrow \theta_{0,1} = \frac{dq}{q} + b_1 dt,$$

$$d\theta_{0,1} = \theta_{0,2} \wedge \theta_{0,0} \Rightarrow \theta_{0,2} = db_1 + b_2 dt,$$

$$d\theta_{2,0} = \theta_{0,3} \wedge \theta_{0,0} - \theta_{0,1} \wedge \theta_{0,2} \Rightarrow \theta_{0,3} = \dots,$$

... ...

Lax representations & exotic cohomology

THEOREM.

$$H^1(Sym(\mathcal{E})) = \mathbb{R} \alpha,$$

$$H_{\lambda \alpha}^2(Sym(\mathcal{E})) = \begin{cases} \mathbb{R} [\Omega], & \lambda = -3, \\ \{0\}, & \lambda \neq -3, \end{cases}$$

where

$$\Omega = \theta_{3,1} \wedge \theta_{0,0} + \frac{2}{3} \theta_{2,1} \wedge \theta_{1,0} + \frac{1}{3} \theta_{1,1} \wedge \theta_{2,0}.$$

COROLLARY. Equation

$$d\omega = 3\alpha \wedge \omega + \Omega$$

is compatible with the structure equations of $Sym(\mathcal{E})$.

REMARK. Denote $\omega = \theta_{3,0} \Rightarrow \Theta_3 = \sum_{j=0}^{\infty} \frac{h^j}{j!} \theta_{3,j}$.

Lax representations & exotic cohomology

Integrate

$$d\theta_{3,0} = 3\alpha \wedge \theta_{3,0} + \theta_{3,1} \wedge \theta_{0,0} + \frac{2}{3}\theta_{2,1} \wedge \theta_{1,0} + \frac{1}{3}\theta_{1,1} \wedge \theta_{2,0}$$

\Rightarrow

$$\theta_{3,0} = p^3 \left(dv - v_x dx - \left(\frac{1}{3}v_x^3 - u_x v_x - u_y \right) dt - \left(\frac{1}{2}v_x^2 - u_x \right) dy \right)$$

the Wahlquist–Estabrook form of the Lax representation

$$\begin{cases} v_t &= \frac{1}{3}v_x^3 - u_x v_x - u_y, \\ v_y &= \frac{1}{2}v_x^2 - u_x \end{cases}$$

for the potential KhZ equation (G.M. Kuz'mina, 1967;
J. Gibbons, 1988; I.M. Krichever, 1988).

Lax representations & exotic cohomology

REMARK. The structure equations for $Sym(\mathcal{E})$:

$$d\alpha = 0,$$

$$d\Theta_0 = \nabla\Theta_0 \wedge \Theta_0,$$

$$d\Theta_1 = \alpha \wedge \Theta_1 + \nabla\Theta_1 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_0 \wedge \Theta_1,$$

$$d\Theta_2 = 2\alpha \wedge \Theta_2 + \nabla\Theta_2 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_1 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_0 \wedge \Theta_2,$$

$$d\Theta_3 = 3\alpha \wedge \Theta_3 + \nabla\Theta_3 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_2 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_1 \wedge \Theta_2,$$

$$d\Theta_4 = 4\alpha \wedge \Theta_4 + \nabla\Theta_4 \wedge \Theta_0 + \frac{2}{3}\nabla\Theta_3 \wedge \Theta_1 + \frac{1}{3}\nabla\Theta_2 \wedge \Theta_2 - \frac{1}{3}\nabla\Theta_0 \wedge \Theta_4,$$

can be written in the form

$$d\alpha = 0,$$

$$d\Theta_k = k\alpha \wedge \Theta_k + \sum_{m=0}^k \left(1 - \frac{1}{3}m\right) \nabla\Theta_{k-m} \wedge \Theta_m, \quad 0 \leq k \leq 4.$$

Lax representations & exotic cohomology

DEFINITION. For $n \in \mathbb{N}$ and $\varepsilon \in \mathbb{R}$ denote by $\mathfrak{G}(n, \varepsilon)$ the Lie algebra with the structure equations

$$d\alpha = 0,$$

$$d\Theta_k = k \alpha \wedge \Theta_k + \sum_{m=0}^k (1 + \varepsilon m) \nabla \Theta_{k-m} \wedge \Theta_m, \quad 0 \leq k \leq n,$$

REMARK. $\mathfrak{G}(n, \varepsilon) = (\mathbb{R}_{n+1}[s] \otimes C^\omega(\mathbb{R})) \rtimes \mathbb{R} Y$,

where

- $\mathbb{R}_{n+1}[s] = \mathbb{R}[s]/\langle s^{n+1} = 0 \rangle$;
- $C^\omega(\mathbb{R})$ is the space of real-analytic functions of t ;
- the Lie bracket on $\mathbb{R}_{n+1}[s] \otimes C^\omega(\mathbb{R})$ is

$$[f, g]_\varepsilon = f g_t - g f_t + \varepsilon s (f_s g_t - g_s f_t);$$

- $Y = s \partial_s$.

REMARK. $\mathfrak{G}(n, \varepsilon)$ is a deformation of $\mathfrak{G}(n, 0)$.

Lax representations & exotic cohomology

OBSERVATION. Suppose $\varepsilon = -\frac{1}{r}$ with $r \in \mathbb{N}$ and $n > r$. Then the 1-form $\theta_{r,0}$ has only two entries in the structure equations

$$d\alpha = 0,$$

$$d\Theta_k = k \alpha \wedge \Theta_k + \sum_{m=0}^k \left(1 - \frac{m}{r}\right) \nabla \Theta_{k-m} \wedge \Theta_m \quad (*)$$

of $\mathfrak{G}(n, -\frac{1}{r})$, namely, the first equation from the series of equations for Θ_r is of the form

$$d\theta_{r,0} = r \alpha \wedge \theta_{r,0} + \Psi_r, \quad (**)$$

where neither Ψ_r nor the other equations in $(*)$ contain $\theta_{r,0}$.

CONCLUSION. Remove $(**)$ from $(*)$. Denote by $\tilde{\mathfrak{G}}(n, -\frac{1}{r})$ the Lie algebra with the obtained structure equations. Then

$$H_{-r\alpha}^2(\tilde{\mathfrak{G}}(n, -\frac{1}{r})) = \mathbb{R}[\Psi_r],$$

and $\mathfrak{G}(n, -\frac{1}{r})$ is an extension of $\tilde{\mathfrak{G}}(n, -\frac{1}{r})$ associated to $(**)$.

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{G}(5, -\frac{1}{4})$ — integrate the structure equations:

$$\theta_{0,0} = \frac{1}{4} q^4 dt, \quad \theta_{1,0} = \frac{1}{3} p q^3 (dy + a dt),$$

$$\theta_{2,0} = \frac{1}{2} p^2 q^2 (dx + 2a dy + (3a^2 - 2u_z) dt),$$

$$\theta_{3,0} = p^3 q (dz + a dx + (a^2 - u_z) dy + (a^3 - 2a u_z - u_x) dt),$$

$$\theta_{5,0} = p^5 q^{-1} (du - u_t dt - u_x dx - u_y dy - u_z dz).$$

Then integrate the equation for $\theta_{4,0}$ and rename $a = v_z$:

$$\begin{aligned} \theta_{4,0} = & -p^4 \left(dv - \left(\frac{1}{4} v_z^4 - u_z v_z^2 - u_x v_z - u_y + \frac{1}{2} u_z^2 \right) dt \right. \\ & \left. - \left(\frac{1}{2} v_z^2 - u_z \right) dx - \left(\frac{1}{3} v_z^3 - u_z v_z - u_x \right) dy - v_z dz \right). \end{aligned}$$

Lax representations & exotic cohomology

$$\theta_{4,0} = 0 \Rightarrow$$

$$\begin{cases} v_t &= \frac{1}{4} v_z^4 - u_z v_z^2 - u_x v_z - u_y + \frac{1}{2} u_z^2, \\ v_y &= \frac{1}{3} v_z^3 - u_z v_z - u_x, \\ v_x &= \frac{1}{2} v_z^2 - u_z. \end{cases}$$

This is the Lax representation for the second system from the dKP hierarchy

$$\begin{cases} u_{xx} &= u_{yz} + u_z u_{zz}, \\ u_{xy} &= u_{tz} + u_z u_{xz} + u_x u_{zz}, \\ u_{yy} &= u_{tx} + u_x u_{xz} + u_z^2 u_{zz}. \end{cases}$$

- V.E. Zakharov, 1980
- P.D. Lax, C.D. Levermore, 1983
- Y. Kodama, 1988
- B.A. Kupershmidt, 1990
- ...

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{G}(6, -\frac{1}{5})$

$$\begin{cases} v_t &= \frac{1}{5}v_s^5 - u_s v_s^3 - u_z v_s^2 + (u_s^2 - u_x) v_s + u_z u_s - u_y, \\ v_y &= \frac{1}{4}v_s^4 - u_s v_s^2 - u_z v_s - u_x + \frac{1}{2}u_s^2, \\ v_x &= \frac{1}{3}v_s^3 - u_s v_s - u_z, \\ v_z &= \frac{1}{2}v_s^2 - u_s \end{cases}$$

\Rightarrow

$$\begin{cases} u_{zz} &= u_{xs} + u_s u_{ss}, \\ u_{xz} &= u_{ys} + u_s u_{zs} + u_z u_{ss}, \\ u_{yz} &= u_{ts} + u_s u_{xs} + u_z u_{zs} + u_x u_{ss}, \\ u_{xx} &= u_{yz} + u_z u_{zs} + u_s^2 u_{ss}, \\ u_{xy} &= u_{tz} + u_z u_{xs} + (u_x + u_s^2) u_{zs} + 2u_z u_s u_{ss}, \\ u_{yy} &= u_{tx} + u_x u_{xs} + 2u_z u_s u_{zs} + (u_z^2 + u_s^3) u_{ss}. \end{cases}$$

Lax representations & exotic cohomology

$$\mathfrak{G}(3, -\frac{1}{2})??$$

For $n > r$ consider the Lie algebra $\mathfrak{H}(n, r)$ with the structure equations

$$d\alpha = 0,$$

$$d\beta = r \alpha \wedge \beta,$$

$$d\Theta_{k'} = k' \alpha \wedge \Theta_{k'} + \sum_{m=0}^{k'} \left(1 - \frac{m}{r}\right) \nabla \Theta_{k'-m} \wedge \Theta_m,$$

$$d\Theta_{k''} = k'' \alpha \wedge \Theta_{k''} + \sum_{m=0}^{k''} \left(1 - \frac{m}{r}\right) \nabla \Theta_{k''-m} \wedge \Theta_m + \beta \wedge \nabla \Theta_{k''-r},$$

$$k' \in \{0, \dots, r-1\}, \quad k'' \in \{r, \dots, n\}.$$

REMARK: $\mathfrak{H}(n, r)$ is the right extension of $\mathfrak{G}(n, -1/r)$ by the outer derivative Z such that $Z: s^k t^j \mapsto j s^{k+r} t^{j-1}$ for $k+r \leq n$, $Z: s^k t^j \mapsto 0$ for $k+r > n$, and $Z \circ Y - Y \circ Z = -r Y$.

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{H}(3, 2)$:

$$H_{\lambda \alpha}^2(\mathfrak{H}(3, 2)) = \begin{cases} \mathbb{R} [\alpha \wedge \beta], & \lambda = -2, \\ \{0\}, & \lambda \neq -2. \end{cases}$$

$$d\tilde{\theta}_{2,0} = 2\alpha \wedge \tilde{\theta}_{2,0} + \theta_{2,1} \wedge \theta_{0,0} + \frac{1}{2}\theta_{1,1} \wedge \theta_{1,0} + \beta \wedge \theta_{0,1} + 2\alpha \wedge \beta$$

Integrate \Rightarrow the Lax representation

$$\begin{cases} v_t &= \frac{1}{2} (e^{v_x} - u_x)^2 - u_y, \\ v_y &= e^{v_x} - u_x. \end{cases}$$

for the equation

$$u_{yy} = u_{tx} + u_x u_{xy}.$$

- V.S. Gerdjikov, 1988,
- M. Błaszkak, 2002,
- M.V. Pavlov, 2003,
- E.V. Ferapontov, A. Moro, V.V. Sokolov, 2008.

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{H}(4, 3)$:

$$H_{\lambda \alpha}^2(\mathfrak{H}(4, 3)) = \begin{cases} \mathbb{R} [\alpha \wedge \beta], & \lambda = -3, \\ \{0\}, & \lambda \neq -3. \end{cases}$$

$$\begin{aligned} d\tilde{\theta}_{3,0} = & 3\alpha \wedge \tilde{\theta}_{3,0} + \theta_{3,1} \wedge \theta_{0,0} + \frac{2}{3}\theta_{2,1} \wedge \theta_{1,0} + \frac{1}{3}\theta_{1,1} \wedge \theta_{2,0} \\ & + \beta \wedge \theta_{0,1} + 3\alpha \wedge \beta \end{aligned}$$

Integrate \Rightarrow the Lax representation

$$\begin{cases} v_t &= \frac{1}{3} (e^{v_x} - u_x)^3 - u_z (e^{v_x} - u_x) - u_y, \\ v_y &= \frac{1}{2} (e^{v_x} - u_x)^2 - u_z, \\ v_z &= e^{v_x} - u_x, \end{cases}$$

for the system

$$\begin{cases} u_{yy} &= u_{tz} + u_z u_{zz}, \\ u_{zz} &= u_{xy} + u_x u_{xz}, \\ u_{yz} &= u_{tx} + u_x u_{xy} + u_z u_{xz}. \end{cases}$$

Lax representations & exotic cohomology

THEOREM: Let $n \geq 2$, then $H_{\lambda\alpha}^2(\mathfrak{G}(n, \varepsilon)) \neq \{0\} \iff \varepsilon = -\frac{2}{r}$ and $\lambda = -r$, where $r \in \{2, \dots, n\}$. In this case

$$H_{-r\alpha}^2(\mathfrak{G}(n, -\frac{2}{r})) = \mathbb{R}[\Phi_r],$$

where

$$\Phi_r = \sum_{m=0}^{[r/2]} (r - 2m) \theta_{r-m,0} \wedge \theta_{m,0}.$$

COROLLARY. Equation

$$d\omega = r\alpha \wedge \omega + \Phi_r.$$

is compatible with the structure equations of $\mathfrak{G}(n, -\frac{2}{r})$.

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{G}(3, -\frac{2}{3})$:

the additional equation

$$d\omega = 3\alpha \wedge \omega + 3\theta_{0,0} \wedge \theta_{3,0} + \theta_{1,0} \wedge \theta_{2,0},$$

integrate \Rightarrow the Lax representation

$$\begin{cases} v_t &= u - (u_x^2 + u_y) v_x, \\ v_y &= x - u_x v_x \end{cases}$$

for

$$u_{yy} = u_{tx} + (u_y - u_x^2) u_{xx} - 3 u_x u_{xy}.$$

- O.M., J. Geom. Phys. 59 (2009), 1461–1475

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{G}(4, -\frac{1}{2})$?? $\mathfrak{H}(4, 2)$:

the additional equation

$$d\omega = 4\alpha \wedge \omega + \theta_{1,0} \wedge \theta_{3,0} + 2\theta_{0,0} \wedge \theta_{4,0} + \beta \wedge \theta_{2,0}$$

\Rightarrow

$$\begin{cases} v_t &= (u_y - u_x u_z - \frac{1}{2} u_z^3) v_z - u, \\ v_y &= (u_x + \frac{1}{2} u_z) v_z + z. \end{cases}$$

\Rightarrow

$$\begin{aligned} u_{yy} &= u_{tx} + u_z u_{xy} - u_y u_{xz} + u_z u_{tz} + 2(u_x + u_z^2) u_{yz} \\ &\quad - (u_x^2 + u_x u_z^2 + u_y u_z + \frac{1}{4} u_z^4) u_{zz}. \end{aligned}$$

Lax representations & exotic cohomology

EXAMPLE. $\mathfrak{G}(5, -\frac{2}{5})$:

Integrate \Rightarrow the Lax representation

$$\begin{cases} v_t = 5 \left(2u - \left(u_x - \frac{4}{3}u_z u_s - \frac{2}{9}u_s^3 \right) v_z - \left(\frac{1}{3}u_y - \frac{11}{9}u_z u_s^2 + u_x u_s - u_z^2 - \frac{13}{81}u_s^4 \right) v_s \right), \\ v_x = 2z + \frac{1}{3}u_s v_z + \left(\frac{2}{9}u_s^2 + u_z \right) v_s, \\ v_y = 6s + \left(3u_z + \frac{2}{3}u_s^2 \right) v_z + \left(3(u_z u_s - u_x) + \frac{13}{27}u_s^3 \right) v_s \end{cases}$$

for ...

Lax representations & exotic cohomology

... the system

$$\left\{ \begin{array}{lcl} u_{xz} & = & u_{ys} - u_s u_{xs} + u_s u_{zz} + \frac{1}{16} (12 u_x + 11 u_s^3 + 12 u_z u_s) u_{ss} \\ & & + 2(u_s^2 + u_z) u_{zs}, \\ u_{xx} & = & \frac{3}{4} (u_s^2 + 8 u_z) u_{xs} + \frac{1}{2} (11 u_s^3 + 18 u_z u_s - 6 u_x) u_{zs} \\ & & - 4 u_{yz} + (4 u_z + 3 u_s^2) u_{zz} + \frac{9}{8} (2 u_z + u_s^2) (u_s^2 - 4 u_z) u_{ss}, \\ u_{tz} & = & 10 u_z u_{ys} - 2 u_{xy} + \frac{1}{8} (u_s^3 - 12 u_x + 4 u_z u_s) u_{xs} \\ & & + \frac{1}{8} (63 u_s^4 + 16 u_z^2 - 48 u_y + 172 u_z u_s^2 - 36 u_x u_s) u_{zs} \\ & & + \frac{1}{8} (18 u_s^5 - 84 u_z^2 u_s + 60 u_x u_z + 19 u_z u_s^3) u_{ss} \\ & & + 2(2 u_s^3 - u_x + 5 u_z u_s) u_{zz}, \\ u_{tx} & = & 8 u_{yy} + \frac{1}{2} (21 u_z u_s^2 + 24 u_z^2 - 5 u_x u_s + 4 u_s^4 - 12 u_y) u_{xs} \\ & & + \frac{1}{8} (7 u_s^5 - 144 u_z^2 u_s - 32 u_x u_z - 32 u_z u_s^3 - 32 u_x u_s^2) u_{zs} \\ & & - \frac{1}{32} (372 u_z u_s^4 + 48 u_x u_s u_z + 44 u_x u_s^3 + 576 u_z^3 + 1008 u_z^2 u_s^2 \\ & & - 96 u_x^2 + 31 u_s^6) u_{ss} + (u_s^4 - 2 u_x u_s - 8 u_z^2) u_{zz} + 10 u_x u_{ys}, \\ u_{ts} & = & 8 u_{yz} + \frac{1}{2} (u_s^2 + 4 u_z) u_{xs} + 10 u_s u_{ys} - (22 u_z u_s + 9 u_s^3 - 4 u_x) u_{zs} \\ & & - 4(2 u_z + u_s^2) u_{zz} - \frac{1}{2} (21 u_z u_s^2 - 6 u_x u_s + 8 u_s^4 + 12 u_y) u_{ss}. \end{array} \right.$$

Conclusion & outlook

- The approach based on the exotic cohomology of symmetry pseudo-groups is successful in both describing known Lax representations and deriving new ones.
- It gives the solution to the problem of existence of a Lax representation in internal terms of the PDE and allows one to eliminate apriori assumptions about the possible form of the Lax representation.
- The approach is universal and can be used to analyze a lot of equations or Lie algebras with nontrivial second exotic cohomology.

Conclusion & outlook

Generalizations:

- to describe right extensions of $\mathfrak{G}(n, \varepsilon)$ (to compute $H^1(\mathfrak{G}(n, \varepsilon), \mathfrak{G}(n, \varepsilon))$);
- to replace vector fields on \mathbb{R} by vector fields on \mathbb{R}^n in the constructions above. For example, Hamiltonian vector fields on $\mathbb{R}^2 \Rightarrow$ the heavenly equations and related equations (B. Kruglikov, O.M., 2012, 2015);
- $\alpha^1, \dots, \alpha^m$ instead of α ,
$$d\alpha^i = \frac{1}{2} c_{jk}^i \alpha^j \wedge \alpha^k$$
 instead of $d\alpha = 0$.
- ...