

# Low-dimensional cohomology of current Lie algebras

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September 7, 2009

## What is a Lie algebra?

anticommutativity:  $[x, y] = -[y, x]$

Jacobi identity:  $[[x, y], z] + [[z, x], y] + [[y, z], x] = 0$

Example: algebra of all  $n \times n$  matrices under  $[X, Y] = XY - YX$

Another (boring) example: *abelian* Lie algebra:  $[x, y] = 0$

Another (interesting) example:  $Der(A)$  for any algebra  $A$

$D : A \rightarrow A$  is a *derivation of A* if

$D(ab) = D(a)b + aD(b)$  for any  $a, b \in A$

$[D_1, D_2] = D_1 \circ D_2 - D_2 \circ D_1$

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## What is a current Lie algebra?

$L$  - Lie algebra     $A$  - associative commutative algebra

$L \otimes A$

$[x \otimes a, y \otimes b] = [x, y] \otimes ab$     for  $x, y \in L, a, b \in A$ .

## What current Lie algebras are good for?

### Kac-Moody algebras

$$\mathfrak{g} \otimes \mathbb{C}[t, t^{-1}] + \mathbb{C}t \frac{d}{dt} + \mathbb{C}z$$

$$[x \otimes f, y \otimes g] = [x, y] \otimes fg + (x, y) \operatorname{Res} \frac{df}{dt} g z$$

for  $x, y \in \mathfrak{g}$ ,  $f, g \in \mathbb{C}[t, t^{-1}]$

$(\cdot, \cdot)$  - symmetric invariant bilinear form on  $\mathfrak{g}$

$$([x, y], z) = (x, [z, y])$$

example:  $(X, Y) = \operatorname{Tr}(XY)$  on the matrix algebra

It is a *central extension* of the current Lie algebra  $\mathfrak{g} \otimes \mathbb{C}[t, t^{-1}]$ :

$$0 \rightarrow Z \rightarrow (\text{central extension}) \rightarrow L \rightarrow 0$$

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### Modular semisimple Lie algebras

$$S \otimes K[x_1, \dots, x_n] / (x_1^p, \dots, x_n^p) + 1 \otimes D$$

## What current Lie algebras are good for? (cont.)

### Physics

**Gauge theory:** how point particles transform as they move along paths in spacetime:



spacetime = smooth manifold  $M$ , for example, a cylinder  $S^1 \times \mathbb{R}$   
 transformation = element of a smooth (Lie) group  $G$  acting on  $M$ .

### String theory:

string = (bunch of) loops

gauge group = loop group {smooth functions  $S^1 \rightarrow G$ }.

*Loop algebra:* {smooth functions  $S^1 \rightarrow L$ } =  $L \otimes \mathbb{R}[t, t^{-1}]$

### Quantum mechanics:

Phases are unobservable, so one considers representations of groups “up to a phase”, i.e. *projective representations* = representations of a central extension.

Central extension of a loop algebra = Kac-Moody algebra.

## What is a cohomology of Lie algebras?

$$C^0(L, M) \xrightarrow{d} C^1(L, M) \xrightarrow{d} C^2(L, M) \xrightarrow{d} C^3(L, M) \xrightarrow{d} \dots$$

$$C^n(L, M) = \{\text{skew-symmetric multilinear maps} : L \times \dots \times L \rightarrow M\}$$

$$d : C^n(L, M) \rightarrow C^{n+1}(L, M)$$

$$d\varphi(x_1, \dots, x_{n+1})$$

$$= \sum_{1 \leq i < j \leq n+1} (-1)^{i+j-1} \varphi([x_i, x_j], x_1, \dots, \widehat{x}_i, \dots, \widehat{x}_j, \dots, x_{n+1})$$

$$+ \sum_{i=1}^{n+1} (-1)^i x_i \bullet \varphi(x_1, \dots, \widehat{x}_i, \dots, x_n)$$

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## Low-dimensional interpretations

- ▶ Abelian extensions

- ▶ Derivations

- ▶ Deformations



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$L$  - Lie algebra,  $M$  -  $L$ -module

$0 \rightarrow M \rightarrow ? \rightarrow L \rightarrow 0$  described by  $H^2(L, M)$

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- ▶ Derivations

derivations = 1-cocycles

$$D([x, y]) - [x, D(y)] + [y, D(x)] = 0$$

inner derivations = 1-coboundaries

$$D(x) = [x, a]$$

outer derivations =  $H^1(L, L)$

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### ► Deformations

$L$  over  $K \rightsquigarrow \mathcal{L}$  over  $K((t))$

$$\{x, y\} = [x, y] + \varphi_1(x, y)t + \varphi_2(x, y)t^2 + \dots$$

“infinitesimal” deformations =  $H^2(L, L)$

obstructions to “integrability” =  $H^3(L, L)$

(Gerstenhaber, 1960s)

## What cohomology of Lie algebras is good for? (cont.)

### Combinatorial identities

$$\mathcal{C} : C_0 \xrightarrow{d} C_1 \xrightarrow{d} C_2 \xrightarrow{d} C_3 \xrightarrow{d} \dots$$

$$\text{Euler-Poincaré characteristic } \chi(\mathcal{C}) = \sum_{n \geq 0} (-1)^n \dim C_n$$

$$\text{Euler-Poincaré principle: } \chi(\mathcal{C}) = \chi(H^*(\mathcal{C})).$$

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$$\prod_{n=1}^{\infty} (1 - t^n) = 1 + \sum_{n=1}^{\infty} (-1)^n (t^{\frac{3n^2-n}{2}} + t^{\frac{3n^2+n}{2}})$$

Euler, 1740s – conjectured

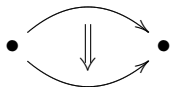
Garland & Lepowsky, 1975-1976 – proved using cohomology of some subalgebras of  $\mathfrak{g} \otimes \mathbb{C}[t, t^{-1}]$ .

## What cohomology of Lie algebras is good for? (cont.)

### 2-Lie algebras

"Categorified" Lie algebras = Lie-like structures on a category in the category of vector spaces (i.e. objects and morphisms are vector spaces)

Used in "higher gauge theory": how strings transform as they move along surfaces in spacetime:



Classified in terms of  $H^3$  of ordinary Lie algebras.  
(Baez & Co., 2002-2009)

What is known about (co)homology of some particular current Lie algebras?

$H^*$  of  $\mathfrak{g} \otimes \mathbb{C}[t, t^{-1}]$ ,  $\mathfrak{g} \otimes \mathbb{C}[t]$ ,  $\mathfrak{g} \otimes \mathbb{C}[t]/(t^n)$ , etc.

(Feigin, Garland, Hanlon, Lepowsky, and others, 1975–1996)

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$H_*(gl(A)) \simeq \bigwedge(HC_*(A))$  and additive K-theory (Tsygan, 1983 and Loday–Quillen, 1984)

*Cyclic (co)homology:*

$$HC^1(A) = \{\alpha : A \times A \rightarrow K \mid \alpha(ab, c) + \alpha(ca, b) + \alpha(bc, a) = 0\}$$



## How cyclic cohomology appears in current Lie algebras cohomology?

Let  $\varphi \otimes \alpha \in Z^2(L \otimes A, K)$ ,  $\varphi : L \times L \rightarrow K$ ,  $\alpha : A \times A \rightarrow K$ :

$$\begin{aligned} & \varphi([x, y], z) \otimes \alpha(ab, c) \\ & + \varphi([z, x], y) \otimes \alpha(ca, b) \\ & + \varphi([y, z], x) \otimes \alpha(bc, a) = 0 \end{aligned}$$

for any  $x, y, z \in L$ ,  $a, b, c \in A$ .

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for any  $x, y, z \in L$ ,  $a, b, c \in A$ .

But what for the general cocycle  $\sum_{i \in I} \varphi_i \otimes \alpha_i \in Z^n(L \otimes A)$ ?

## How to compute cohomology of “general” current Lie algebras?

Task: to “compute”  $H^n(L \otimes A, M \otimes V)$ .

$$\begin{aligned} Z^n(L \otimes A, M \otimes V) &\subset \text{Hom}((L \otimes A)^{\otimes n}, M \otimes V) \\ &\simeq \text{Hom}(L^{\otimes n}, M) \otimes \text{Hom}(M^{\otimes n}, V) \end{aligned}$$

Various symmetrizations of the cocycle equation  $d\Phi = 0$  lead to conditions  $(S \otimes T)\Phi = 0$ , where

$S \in \text{Hom}(\text{Hom}(L^{\otimes n}, M))$ ,  $T \in \text{Hom}(\text{Hom}(A^{\otimes n}, V))$ .

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For example: fully symmetrize the cocycle equation

$d\Phi(x_1 \otimes a_1, x_2 \otimes a_2, x_3 \otimes a_3) = 0$  with respect to  $x_i$ 's, where

$\Phi = \sum_{i \in I} \varphi_i \otimes \alpha_i$ ,  $\varphi_i : L \times L \rightarrow M$ ,  $\alpha_i : A \times A \rightarrow V$ :

$$\begin{aligned} \sum_{i \in I} \left( (x_1 \bullet \varphi_i(x_2, x_3) + x_1 \otimes \varphi_i(x_3, x_2) \right. \\ + x_2 \bullet \varphi_i(x_1, x_3) + x_2 \otimes \varphi_i(x_3, x_1) \\ + x_3 \bullet \varphi_i(x_1, x_2) + x_3 \otimes \varphi_i(x_2, x_1)) \\ \left. \otimes (-a_1 \bullet \alpha_i(a_2, a_3) + a_2 \bullet \alpha_i(a_1, a_3) - a_3 \bullet \alpha_i(a_1, a_2)) \right) = 0 \end{aligned}$$

## What is known about (co)homology of “general” current Lie algebras?

Nice formulae:

- ▶  $H^1(L \otimes A, M \otimes V) \simeq H^1(L, M) \otimes V + \text{Hom}_L(L, M) \otimes \text{Der}(A, V)$   
(Zusmanovich, 2005)
- ▶  $H^2(L \otimes A, K) \simeq H^2(L, K) \otimes A^* + B(L) \otimes HC^1(A)$   
(Haddi, 1992)  
(both assuming  $[L, L] = L$ )
- ▶ If  $\mathfrak{g}$  is a simple Lie algebra ( $p = 0$ ), then  
 $H^2(\mathfrak{g} \otimes A, \mathfrak{g} \otimes A) \simeq \text{Har}^2(A, A)$  (Cathelineau, 1987)
- ▶ If  $W_1(n)$  is the modular Zassenhaus algebra, then

$$\begin{aligned} & H^2(W_1(n) \otimes A, W_1(n) \otimes A) \\ & \simeq H^2(W_1(n), W_1(n)) \otimes A + \text{Der}(A) + \text{Der}(A) + \text{Har}^2(A, A) \end{aligned}$$

(Zusmanovich, 2003)

- ▶  $H^3(\mathfrak{g} \otimes A, K) \simeq HC^2(A)$  or  $HD^2(A)$  (Cathelineau, 1987)

## Application to structure theory of modular Lie algebras

A bit more about  $H^2(W_1(n) \otimes A, W_1(n) \otimes A) \dots$

$$W_1(n) = \langle e_{-1}, e_0, e_1, \dots, e_{p^n-2} \rangle,$$

$$[e_i, e_j] = \left( \binom{i+j+1}{j} - \binom{i+j+1}{i} \right) e_{i+j}.$$

Description of modular semisimple Lie algebras with a solvable maximal subalgebra (Weisfeiler, 1984): filtered deformations of  $W_1(n) \otimes K[x_1, \dots, x_n]/(x_1^p, \dots, x_n^p) + 1 \otimes D$ .

Filtered deformation: (graded algebra)  $\rightsquigarrow$  (filtered algebra)

filtered algebra:  $\mathcal{L} = \mathcal{L}_{-1} \supset \mathcal{L}_0 \supset \mathcal{L}_1 \supset \dots$

associated graded algebra:  $L = \bigoplus_{i \geq -1} \mathcal{L}_i / \mathcal{L}_{i+1}$

# What is known about (co)homology of “general” current Lie algebras? (cont.)

Ugly formulae: some part (not all!) of  $H^2(L \otimes A, M \otimes V)$  is isomorphic to

$$\begin{aligned}
 H^2(L, M) \otimes V + H_M^2(L) \otimes \frac{\text{Hom}(A, V)}{V \oplus \text{Der}(A, V)} + \mathcal{H}(L, M) \otimes \text{Der}(A, V) + \mathcal{B}(L, M) \otimes \frac{\text{Har}^2(A, V)}{\mathcal{P}_+(A, V)} \\
 + C^2(L, M)^L \otimes \mathcal{P}_+(A, V) + \mathcal{X}(L, M) \otimes \frac{\mathcal{A}(A, V)}{\mathcal{P}_+(A, V)} + \mathcal{F}(L, M) \otimes \frac{D(A, V)}{\text{Der}(A, V)} \\
 + \text{Poor}_-(L, M) \otimes \frac{S^2(A, V)}{\text{Hom}(A, V) + D(A, V) + \text{Har}^2(A, V) + \mathcal{A}(A, V)}
 \end{aligned}$$

where:

$$d^1 \varphi(x, y, z) = \varphi([x, y], z) + \varphi;$$

$$\varphi \alpha(a, b, c) = \alpha(ab, c) + \varphi;$$

$$D\alpha(a, b, c) = a \bullet \alpha(b, c) + \varphi;$$

$$\mathcal{B}(L, M) = \{\varphi \in C^2(L, M) \mid \varphi([x, y], z) + z \bullet \varphi(x, y) = 0; d^1 \varphi(x, y, z) = 0\};$$

$$Q^2(L, M) = \{d\psi \mid \psi \in \text{Hom}(L, M); x \bullet \psi(y) = y \bullet \psi(x)\};$$

$$H_M^2(L) = (Z^2(L, M^L) + Q^2(L, M)) / Q^2(L, M);$$

$$\mathcal{F}(L, M) = \{\varphi \in C^2(L, M) \mid \varphi(x, y) = \psi([x, y]) - \frac{1}{2}x \bullet \psi(y) + \frac{1}{2}y \bullet \psi(x) \text{ for } \psi \in \text{Hom}(L, M)\};$$

$$\mathcal{H}(L, M) = (\mathcal{X}(L, M) + \mathcal{F}(L, M)) / \mathcal{F}(L, M).$$

$$\mathcal{X}(L, M) = \{\varphi \in C^2(L, M) \mid 2\varphi([x, y], z) = z \bullet \varphi(x, y); \varphi([x, y], z) = \varphi([z, x], y)\};$$

$$\mathcal{T}(L, M) = \{\varphi \in C^2(L, M) \mid 3\varphi([x, y], z) = 2z \bullet \varphi(x, y); \varphi([x, y], z) = \varphi([z, x], y)\};$$

$$\text{Poor}_-(L, M) = \{\varphi \in C^2(L, M^L) \mid \varphi([L, L], L) = 0\};$$

$$D(A, V) = \{\beta \in \text{Hom}(A, V) \mid \beta(abc) = a \bullet \beta(bc) - bc \bullet \beta(a) + \varphi\};$$

$$\mathcal{P}_+(A, V) = \{\alpha \in S^2(A, V) \mid \alpha(ab, c) = a \bullet \alpha(b, c) + b \bullet \alpha(a, c)\};$$

$$\mathcal{A}(A, V) = \{\alpha \in S^2(A, V) \mid 2D\alpha = \varphi\alpha\}.$$

## How to (methodically) compute cohomology of “general” current Lie algebras?

Cauchy formula:

$$\bigwedge^n (L \otimes A) \simeq \bigoplus_{\lambda \vdash n} Y_\lambda(L) \otimes Y_{\lambda^\sim}(A)$$

$Y_\lambda$  - Schur functor associated with the Young diagram  $\lambda$ .

Examples:

$$Y_{\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}} = \frac{1}{3!} \sum_{\sigma \in \mathcal{S}_3} (-1)^\sigma \sigma$$

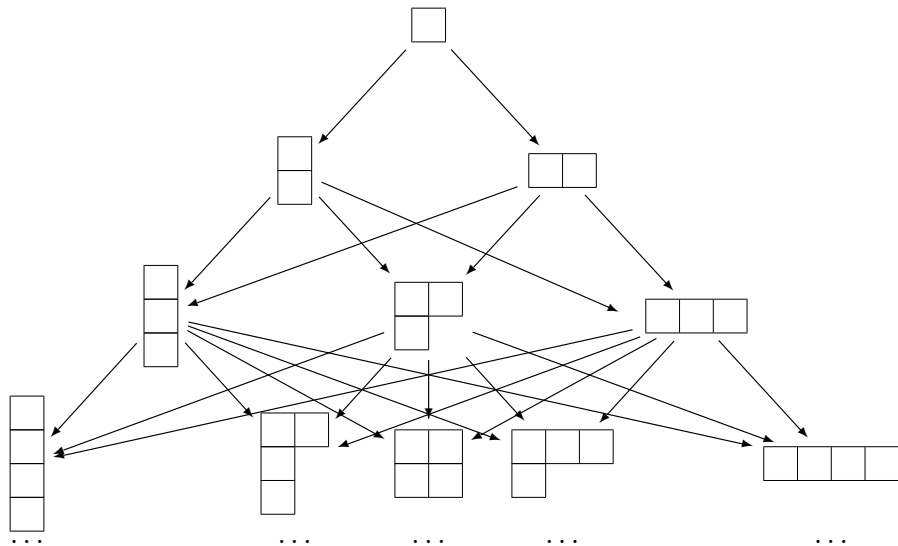
$$Y_{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}} = \frac{1}{3!} \sum_{\sigma \in \mathcal{S}_3} \sigma$$

$$Y_{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \\ \hline \end{array}} = \frac{1}{3} (e + (12) - (13) - (123))$$

$\lambda^\sim$  - obtained from  $\lambda$  by interchanging rows and columns

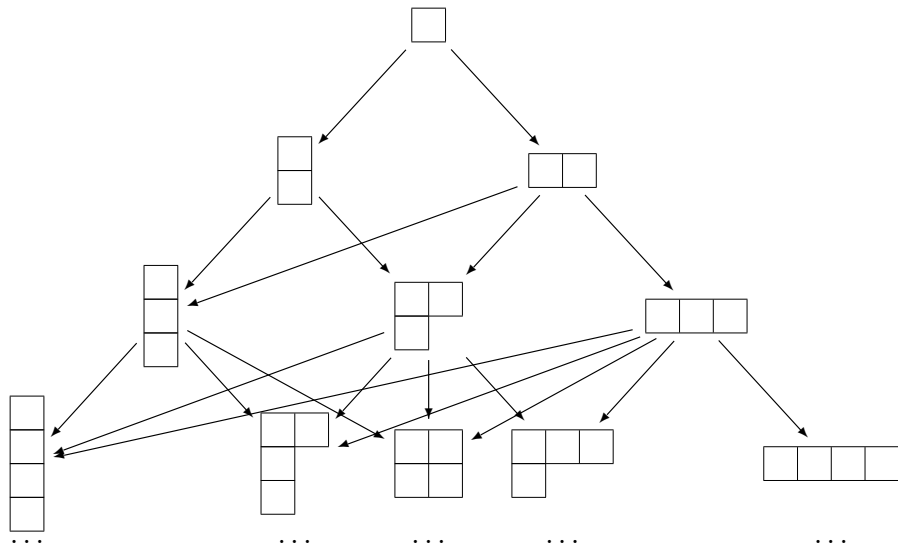


# A spectral sequence...



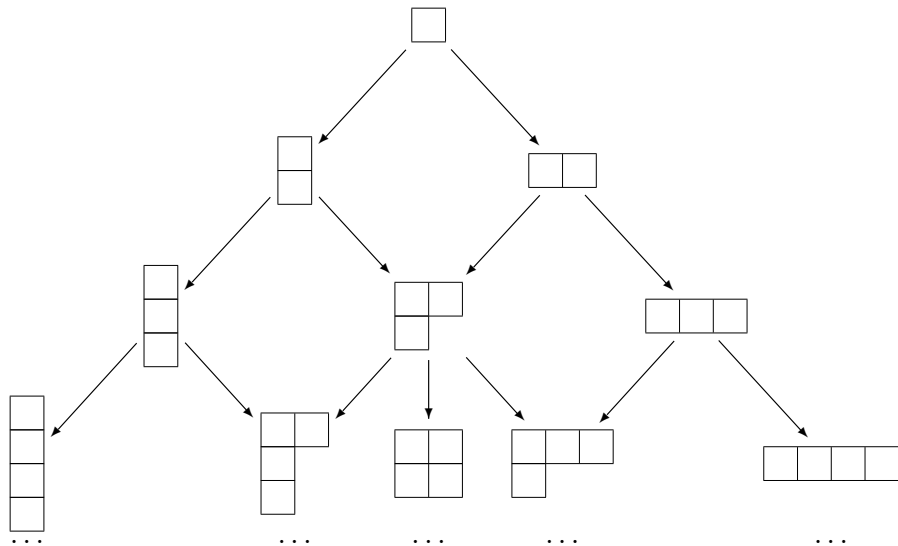
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# A spectral sequence... (abelian $L$ )

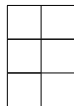


each Young diagram  $\lambda$  represents  $\text{Hom}(Y_\lambda(L), M) \otimes \text{Hom}(Y_\lambda(A), V)$

## A spectral sequence (cont.)

Which arrows do not vanish?

- ▶ going from “right” to “left”
- ▶ the source Young diagram included into the target Young diagram (the only case when  $L$  is abelian)
- ▶ the target Young diagram is of the shape:



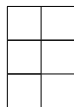
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...



Filtration:  $F^k C^* =$  “closure” under non-vanishing arrows of



$k + 1 \dots$



That's all. Thank you.

Slides at <http://justpasha.org/math/iceland-2009.pdf> .